

Inverting Over-Determined Matrices

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Minnowbrook 2011

Inverting Over-Determined Matrices

Given you know how to invert a square non-singular matrix, how can we invert an over-determined matrix – that is how is a least squares fit done?

Inverting Over-Determined Matrices

Surprisingly, this can be accomplished with a short one-line APL expression.

Even more surprisingly, there is a short (half page) mathematical proof of the validity of this expression by Berthold K. P. Horn:

http://people.csail.mit.edu/bkph/articles/Pseudo_Inverse.pdf

(with an excursion into Matrix Calculus).

Inverting Over-Determined Matrices

Suppose $\mathbf{y} = \mathbf{M}\mathbf{x}$ where \mathbf{M} is a known $\mathbf{n} \times \mathbf{m}$ matrix, \mathbf{y} is a known \mathbf{n} -vector and \mathbf{x} is an unknown \mathbf{m} -vector. Mathematicians call these “column vectors”.

A least-squares solution minimizes the error term $(\mathbf{y} - \mathbf{M}\mathbf{x})$. That is, we want to find \mathbf{x} that minimizes

$$\begin{aligned} f(\mathbf{x}) &= \|\mathbf{y} - \mathbf{M}\mathbf{x}\|^2 \\ &= (\mathbf{y} - \mathbf{M}\mathbf{x})^T (\mathbf{y} - \mathbf{M}\mathbf{x}) \\ &= (\mathbf{y}^T - \mathbf{x}^T \mathbf{M}^T) (\mathbf{y} - \mathbf{M}\mathbf{x}) \\ &= \mathbf{y}^T \mathbf{y} - \mathbf{y}^T \mathbf{M}\mathbf{x} - \mathbf{x}^T \mathbf{M}^T \mathbf{y} + \mathbf{x}^T \mathbf{M}^T \mathbf{M}\mathbf{x} \end{aligned}$$

How do we find a minimum of this (matrix!) function?

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Calculus to the rescue!

One of the lessons of calculus is that to solve a minimization problem, we differentiate the function and set the result equal to zero.

Except, how do we differentiate a matrix function?

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Fortunately, differential calculus has been extended to matrices in the form of Matrix Calculus. Here's (almost) everything you need to know about differentiating a matrix function:

For more details, see

	$f(\mathbf{x})$	$f'(\mathbf{x})$
1	\mathbf{Ax}	\mathbf{A}^T
2	$\mathbf{x}^T\mathbf{A}$	\mathbf{A}
3	$\mathbf{x}^T\mathbf{Ax}$	$(\mathbf{A}+\mathbf{A}^T)\mathbf{x}$

<http://www.colorado.edu/engineering/cas/courses.d/IFEM.d/IFEM.AppD.d/IFEM.AppD.pdf>

Inverting Over-Determined Matrices

$$0: f(\mathbf{x}) = \mathbf{y}^T \mathbf{y} - \mathbf{y}^T \mathbf{M} \mathbf{x} - \mathbf{x}^T \mathbf{M}^T \mathbf{y} + \mathbf{x}^T \mathbf{M}^T \mathbf{M} \mathbf{x}$$

Differentiating w.r.t. \mathbf{x} (using the rules of Matrix Calculus) and setting the result equal to zero yields

$$1: f'(\mathbf{x}) = \mathbf{0} - (\mathbf{y}^T \mathbf{M})^T - \mathbf{M}^T \mathbf{y} + 2\mathbf{M}^T \mathbf{M} \mathbf{x} = \mathbf{0}$$

$$2: -2\mathbf{M}^T \mathbf{y} + 2\mathbf{M}^T \mathbf{M} \mathbf{x} = \mathbf{0}$$

$$3: \mathbf{M}^T \mathbf{M} \mathbf{x} = \mathbf{M}^T \mathbf{y}$$

$$4: \mathbf{x} = (\mathbf{M}^T \mathbf{M})^{-1} \mathbf{M}^T \mathbf{y}$$

$$(\mathbf{0}(\mathbf{0M}) + \cdot \times \mathbf{M}) + \cdot \times \mathbf{0M}$$

$$\leftrightarrow (\mathbf{0M})\mathbf{0}(\mathbf{0M}) + \cdot \times \mathbf{M}$$

$$\leftrightarrow (\mathbf{0M})\mathbf{0M}\mathbf{0}\mathbf{0M} \quad (\text{Roy})$$

	$f(\mathbf{x})$	$f'(\mathbf{x})$
1	\mathbf{Ax}	\mathbf{A}^T
2	$\mathbf{x}^T \mathbf{A}$	\mathbf{A}
3	$\mathbf{x}^T \mathbf{A} \mathbf{x}$	$(\mathbf{A} + \mathbf{A}^T) \mathbf{x}$